

Exercise 05 — Solution Reference

I2DL — Introduction to Deep Learning

[exercise_code/networks/layer.py](#)

```
#####  
# TODO: #  
# Implement the forward pass of Sigmoid activation function #  
#####  
out = 1 / (1 + np.exp(-x))  
cache = out  
#####  
# END OF YOUR CODE #  
#####
```

```
#####  
# TODO: #  
# Implement the backward pass of Sigmoid activation function #  
#####  
dx = dout * cache * (1 - cache)  
#####  
# END OF YOUR CODE #  
#####
```

```
#####  
# TODO: #  
# Implement the forward pass of Relu activation function #  
#####  
out = np.maximum(x, 0)  
cache = x  
#####  
# END OF YOUR CODE #  
#####
```

```
#####  
# TODO: #  
# Implement the backward pass of Relu activation function #  
#####  
x = cache  
dx = dout
```

```

dx[x < 0] = 0
#####
#                                     END OF YOUR CODE                               #
#####

```

```

#####
# TODO: Implement the affine forward pass. Store the result in out. #
# You will need to reshape the input into rows. #
#####
x_resaped = np.reshape(x, (x.shape[0], -1))
out = x_resaped.dot(w) + b
#####
#                                     END OF YOUR CODE                               #
#####

```

```

#####
# TODO: Implement the affine backward pass. #
#####

dw = (np.reshape(x, (x.shape[0], -1)).T).dot(dout)
dw = np.reshape(dw, w.shape)

db = np.sum(dout, axis=0, keepdims=False)

dx = dout.dot(w.T)
dx = np.reshape(dx, x.shape)
#####
#                                     END OF YOUR CODE                               #
#####

```

[exercise_code/networks/optimizer.py](#)

```

#####
# TODO: Implement the momentum update formula. Store the updated #
# value in the next_w variable. You should also use and update the #
# velocity v. #
#####
mu = config['momentum']
learning_rate = lr
v = mu * v - learning_rate * dw
next_w = w + v
#####
#                                     END OF YOUR CODE                               #
#####

```
